

Interval Robotics

Chapter 2: Subpavings

L. Jaulin



Set inversion

Let $\mathbf{f}: \mathbb{R}^n \rightarrow \mathbb{R}^m$ and let \mathbb{Y} be a subset of \mathbb{R}^m . Set inversion is the characterization of

$$\mathbb{X} = \{\mathbf{x} \in \mathbb{R}^n \mid \mathbf{f}(\mathbf{x}) \in \mathbb{Y}\} = \mathbf{f}^{-1}(\mathbb{Y}).$$

We shall use the following tests;

$$\begin{aligned} \text{(i)} \quad & \mathbf{f}([\mathbf{x}]) \subset \mathbb{Y} \quad \Rightarrow \quad [\mathbf{x}] \subset \mathbb{X} \\ \text{(ii)} \quad & \mathbf{f}([\mathbf{x}]) \cap \mathbb{Y} = \emptyset \quad \Rightarrow \quad [\mathbf{x}] \cap \mathbb{X} = \emptyset. \end{aligned}$$

Boxes for which these tests failed, will be bisected, except if they are too small.

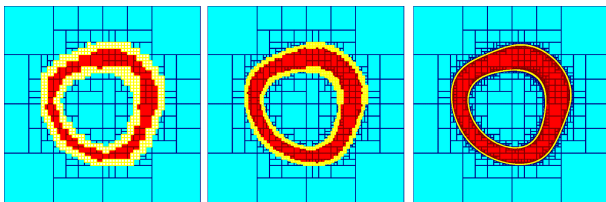
A subpaving of \mathbb{R}^n is a set of non-overlapping boxes of \mathbb{R}^n .
Compact sets \mathbb{X} can be bracketed between inner and outer subpavings:

$$\mathbb{X}^- \subset \mathbb{X} \subset \mathbb{X}^+.$$

Exercise. The set

$$\mathbb{X} = \{(x_1, x_2) \mid x_1^2 + x_2^2 + \sin(x_1 + x_2) \in [4, 9]\}$$

are approximated by \mathbb{X}^- and \mathbb{X}^+ for different accuracies. Denote by $\mathbb{R}, \mathbb{Y}, \mathbb{B}$ the union of red, yellow, blue boxes. Denote by $\partial\mathbb{X}$ the boundary of \mathbb{X} .



$$X^- \cap B = \emptyset$$

yes or no

$$X \cap B \neq \emptyset$$

yes or no

$$X^+ = R \cup Y$$

yes or no

$$\partial X \supset Y$$

yes or no

$$X \setminus (R \cup B) = Y \cap X$$

yes or no

Solution. We have

$$X^- \cap B = \emptyset \quad \rightarrow \quad \text{Yes}$$

$$X \cap B = \emptyset \quad \rightarrow \quad \text{No}$$

$$X^+ = R \cup Y \quad \rightarrow \quad \text{Yes}$$

$$\partial X \supset Y \quad \rightarrow \quad \text{No. Instead, we have } \partial X \subset Y$$

$$X \setminus (R \cup B) = Y \cap X \quad \rightarrow \quad \text{Yes}$$

Set operations such as $Z := X + Y$, $X := \mathbf{f}^{-1}(Y)$, $Z := X \cap Y \dots$
can be approximated by subpaving operations.

Exercise. Consider the set

$$\mathbb{X} = \{\mathbf{x} \in \mathbb{R}^2 \mid x_1^2 + x_2^2 \leq 4\}.$$

Find two subpavings \mathbb{X}^- and \mathbb{X}^+ , both made with a single box, such that

$$\mathbb{X}^- \subset \mathbb{X} \subset \mathbb{X}^+.$$

Solution. We can take

$$\mathbb{X}^- = \left\{ \left[-\sqrt{2}, \sqrt{2} \right]^{\times 2} \right\} \text{ and } \mathbb{X}^+ = \left\{ \left[-2, 2 \right]^{\times 2} \right\}.$$

Here, subpavings are singletons, but it is not the case usually.

If $\mathbf{f}: \mathbb{R}^n \rightarrow \mathbb{R}^m$ and $Y \subset \mathbb{R}^m$.

$$X = \{\mathbf{x} \in \mathbb{R}^n \mid \mathbf{f}(\mathbf{x}) \in Y\} = \mathbf{f}^{-1}(Y).$$

Exercise. Define the set

$$\mathbb{X} = \{\mathbf{x} \in \mathbb{R}^2 \mid x_1 x_2 + \sin x_2 \leq 0 \text{ and } x_1 - x_2 = 1\}.$$

Show that it is a set inversion problem.

Solution. We have

$$\mathbb{X} = \mathbf{f}^{-1}(\mathbb{Y})$$

with

$$\mathbf{f}(\mathbf{x}) = \begin{pmatrix} x_1 x_2 + \sin x_2 \\ x_1 - x_2 \end{pmatrix} \text{ and } \mathbb{Y} = [-\infty, 0] \times \{1\}.$$

- (i) $\mathbf{f}([\mathbf{x}]) \subset \mathbb{Y} \Rightarrow [\mathbf{x}] \subset \mathbb{X}$
- (ii) $\mathbf{f}([\mathbf{x}]) \cap \mathbb{Y} = \emptyset \Rightarrow [\mathbf{x}] \cap \mathbb{X} = \emptyset.$

Boxes for which these tests failed, will be bisected, except if they are too small.

SIVIA

Algorithm Sivia(in: $[\mathbf{x}](0), \mathbf{f}, \mathbb{Y}$)

```
1   $\mathcal{L} := \{[\mathbf{x}](0)\};$   
2  pull  $[\mathbf{x}]$  from  $\mathcal{L}$ ;  
3  if  $[\mathbf{f}]([\mathbf{x}]) \subset \mathbb{Y}$ , draw( $[\mathbf{x}]$ , 'red');  
4  elseif  $[\mathbf{f}]([\mathbf{x}]) \cap \mathbb{Y} = \emptyset$ , draw( $[\mathbf{x}]$ , 'blue');  
5  elseif  $w([\mathbf{x}]) < \varepsilon$ , {draw ( $[\mathbf{x}]$ , 'yellow')};  
6  else bisect  $[\mathbf{x}]$  and push into  $\mathcal{L}$ ;  
7  if  $\mathcal{L} \neq \emptyset$ , go to 2
```

If $\Delta\mathbb{X}$ denotes the union of yellow boxes and if \mathbb{X}^- is the union of red boxes then :

$$\mathbb{X}^- \subset \mathbb{X} \subset \underbrace{\mathbb{X}^- \cup \Delta\mathbb{X}}_{\mathbb{X}^+}.$$

Stack-queue

A *queue* is a list on which two operations are allowed:

- add an element at the end (*push*)
- remove the first element (*pull*).

A *stack* is a list on which two operations are allowed:

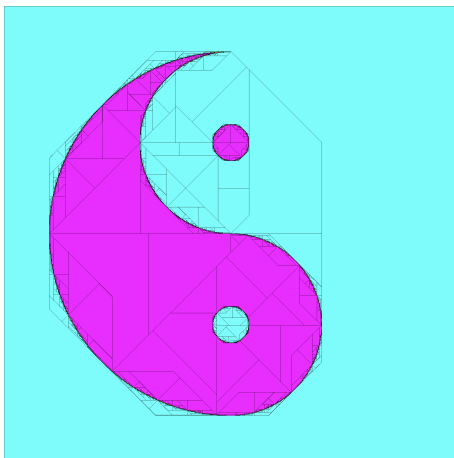
- add an element at the beginning of the list (*stack*)
- remove the first element (*pop*).

Example: Let \mathcal{L} be an empty queue.

k	operation	result
0		$\mathcal{L} = \emptyset$
1	push(\mathcal{L}, a)	$\mathcal{L} = \{a\}$
2	push(\mathcal{L}, b)	$\mathcal{L} = \{a, b\}$
3	$x := \text{pull}(\mathcal{L})$	$x = a, \mathcal{L} = \{b\}$
4	$x := \text{pull}(\mathcal{L})$	$x = b, \mathcal{L} = \emptyset$.

If \mathcal{L} is a stack, the table becomes

k	operation	result
0		$\mathcal{L} = \emptyset$
1	$\text{stack}(\mathcal{L}, a)$	$\mathcal{L} = \{a\}$
2	$\text{stack}(\mathcal{L}, b)$	$\mathcal{L} = \{a, b\}$
3	$x := \text{pop}(\mathcal{L})$	$x = b, \mathcal{L} = \{a\}$
4	$x := \text{pop}(\mathcal{L})$	$x = a, \mathcal{L} = \emptyset.$



Sivia with octogones (made by D. Massé)

Paver

A paver is an algorithm which generates boxes by bisections and classifies them.

Take

$$\mathbb{X} = \{\mathbf{x} \in \mathbb{R}^n \mid t(\mathbf{x}) = 1\} = t^{-1}(1)$$

We want an enclosure of the form

$$\mathbb{X}^- \subset \mathbb{X} \subset \mathbb{X}^+$$

Algorithm Sivia(in: $[\mathbf{x}](0), [t]$)

```
1   $\mathcal{L} := \{[\mathbf{x}](0)\};$   
2  pull( $[\mathbf{x}], \mathcal{L}$ );  
3  if  $[t]([\mathbf{x}]) = 1$ , draw( $[\mathbf{x}], 'red'$ );  
4  elseif  $[t]([\mathbf{x}]) = 0$ , draw( $[\mathbf{x}], 'blue'$ );  
5  elseif  $w([\mathbf{x}]) < \varepsilon$ , {draw ( $[\mathbf{x}], 'yellow'$ )};  
6  else bisect  $[\mathbf{x}]$  into  $[\mathbf{x}](1)$  and  $[\mathbf{x}](2)$ ; push ( $[\mathbf{x}](1), [\mathbf{x}](2), \mathcal{L}$ );  
7  if  $\mathcal{L} \neq \emptyset$ , go to 2
```

Define

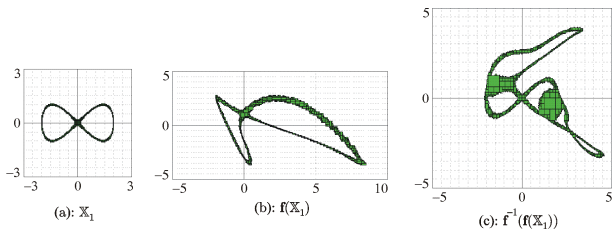
$$\mathbf{f}(x_1, x_2) = \begin{pmatrix} (x_1 - 1)^2 - 1 + x_2 \\ -x_1^2 + (x_2 - 1)^2 \end{pmatrix},$$

and

$$\mathbb{X}_1 = \{(x_1, x_2) \in \mathbb{R}^2 \mid x_1^4 - x_1^2 + 4x_2^2 \in [-0.1, 0.1]\}.$$

We shall compute \mathbb{X}_1 , $\mathbf{f}(\mathbb{X}_1)$ and $\mathbf{f}^{-1} \circ \mathbf{f}(\mathbb{X}_1)$.

Image of a set



Sivia works with other abstract domains (or wrappers).

Application

Exercise. Consider a parabola of the form

$$\phi(\mathbf{p}, t) = p_1 t^2 + p_2 t + p_3.$$

where $\mathbf{p} = (p_1, p_2, p_3)^T$ is an unknown parameter vector. Assume that

$$\phi(\mathbf{p}, 1) \in [2, 3], \quad \phi(\mathbf{p}, 4) \in [5, 6], \quad \phi(\mathbf{p}, 7) \in [8, 9].$$

Show that the set \mathbb{P} of all feasible \mathbf{p} can be defined as a set inversion problem.

Solution. We have

$$\mathbb{P} = \mathbf{f}^{-1}(\mathbb{Y}),$$

where

$$\mathbf{f}(\mathbf{p}) = \begin{pmatrix} \phi(\mathbf{p}, 1) \\ \phi(\mathbf{p}, 4) \\ \phi(\mathbf{p}, 7) \end{pmatrix} = \begin{pmatrix} p_1 + p_2 + p_3 \\ 16p_1 + 4p_2 + p_3 \\ 49p_1 + 7p_2 + p_3 \end{pmatrix}$$

and

$$\mathbb{Y} = [2, 3] \times [5, 6] \times [8, 9].$$

Model : $\phi(\mathbf{p}, t) = p_1 e^{-p_2 t}$.

Prior feasible box for the parameters : $[\mathbf{p}] \subset \mathbb{R}^n$

Measurement times : t_1, t_2, \dots, t_m

Data bars : $[y_1^-, y_1^+], [y_2^-, y_2^+], \dots, [y_m^-, y_m^+]$

$$\mathbb{S} = \{\mathbf{p} \in [\mathbf{p}], \phi(\mathbf{p}, t_1) \in [y_1^-, y_1^+], \dots, \phi(\mathbf{p}, t_m) \in [y_m^-, y_m^+]\}.$$

If

$$\phi(\mathbf{p}) = \begin{pmatrix} \phi(\mathbf{p}, t_1) \\ \vdots \\ \phi(\mathbf{p}, t_m) \end{pmatrix}$$

and




$$[\mathbf{y}] = [y_1^-, y_1^+] \times \cdots \times [y_m^-, y_m^+]$$

then

$$\mathbb{P} = [\mathbf{p}] \cap \phi^{-1}([\mathbf{y}]).$$

References

- 1 Interval analysis [3, 1, 2]
- 2 IAMOOC [2]

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